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state feedback control has to be modified to settle at nonzero values. This can be...

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of the adaptive nonlinear dynamic feedback control proposed in (Hmamed and Radouane, 1983) for multivariable systems in the presence of uncertainty. A multivariable system is decomposed into a set of single-input subsystems and the second Luenberger canonical form is obtained.

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- Feedback Control of Dynamic Systems, Fourth Edition, Franklin, Powell, Emami-Naeini, Prentice Hall, 2002
- Control System Design, Goodwin, Graebe, Salgado, Prentice Hall, 2001.

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A proportional-integral-derivative controller (PID

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controller) is a control loop feedback mechanism control technique widely used in control systems. A PID controller continuously calculates an error value  $e(t)$  as the difference between a desired setpoint and a measured process variable and applies a correction based on proportional, integral, and derivative terms.

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